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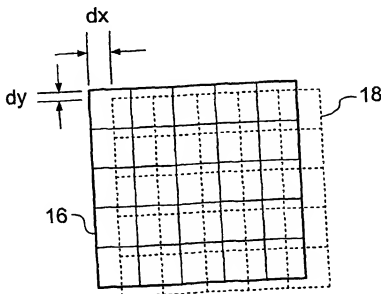
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(54) Title: POSITIONAL MEASUREMENT OF A FEATURE WITHIN AN IMAGE



(57) Abstract: The position of a feature within an image is determined by determining an initial estimate of the feature position to within a fraction of a pixel, translating the feature by an amount equal to that fraction of a pixel, determining a further estimate of the translated feature position to within a fraction of a pixel and summing the pixel fraction of the previous estimate with the further estimate of the position to arrive at a refined estimate of the feature position.

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